

CHAPTRE EIGHT

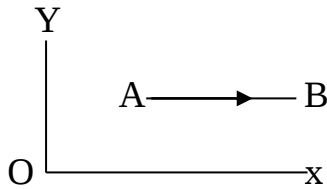
VECTORS

- A vector is a physical quantity which has both magnitude and direction.
- Example are
 - a. A force of 20N acting North.
 - b. A velocity of 5km/h East.

Types of vectors:

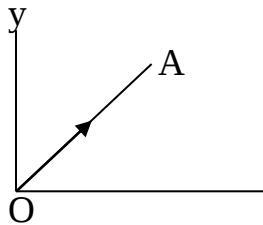
- In general there are two types and these are
 - i. Free vector.
 - ii. Position vector.

Free vector:



- A free vector is a vector which does not pass through any specific position.
- They are usually represented by small letters e.g. $\vec{a}$, $\vec{b}$ and $\vec{c}$

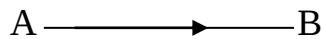
Position vector :



This is a vector which passes through the origin or a specified point.

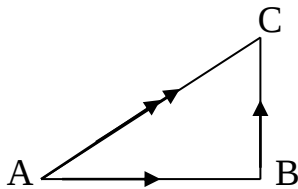
Vector notation:

- A vector may be represented by a line segment as shown next:



- This given vector can be represented by $\overrightarrow{AB}$, $\overline{AB}$, $\underline{AB}$, $\widehat{AB}$, $\sim^{AB}$.

The Triangle law:



According to the triangle law, $\overline{AC} = \overline{AB} + \overline{BC} \Rightarrow \overline{AB} = \overline{AC} - \overline{BC}$ and $\overline{BC} = \overline{AC} - \overline{AB}$

The unit vector:

- This is a vector whose magnitude is one in the direction under consideration.
- The unit vector along a vector $\vec{a}$ is written as $\hat{a}$
- Also the unit vector along a vector $\vec{b}$ is written as $\hat{b}$
- The unit vector along the vector $\overline{BC}$ is written as $\widehat{BC}$
- Consider the vector $A \rightarrow B = 1$
- The vector is written as $\overrightarrow{AB}$ and its unit vector is written as $\widehat{AB}$.

Equal vectors:

- Two vectors are said to be equal if their magnitudes and directions are equal
- Example are $\overline{AB} = 50\text{km/h E}$ and $\overline{CD} = 50\text{km/h E}$.

The negative vector:

- The negative of the vector $\vec{a}$ is written as $-\vec{a}$
- If $-\vec{a}$ is the negative vector of the vector $\vec{a}$, then $\vec{a} + (-\vec{a}) = \vec{0}$.
- The vector $-\vec{a}$ is a vector of the same magnitude as $\vec{a}$, but it is opposite in direction.
- It must be noted that $\overline{AB} + \overline{BA} = \vec{0}$.

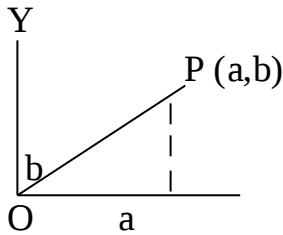
- Also if $\vec{b} = \vec{CD}$, then $-\vec{b} = \vec{DC}$, and $\vec{CD} + \vec{DC} = \vec{0}$.
- If we consider a vector $\vec{CD}$, then its negative vector is $\vec{DC}$.

The zero vector (null vector):

- This is a vector where magnitude is zero and its direction is undefined.
- It is represented by $\vec{0} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

Notation of the magnitude of a vectors:

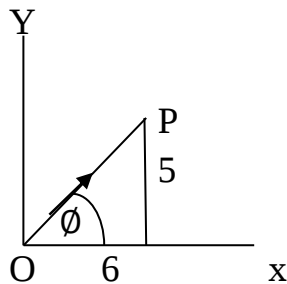
- If $\vec{AB}$ is a vector, then its magnitude is written as $|\vec{AB}|$
- Similarly the magnitude of the vector $\vec{b}$ is written as $|\vec{b}|$
- If $\vec{OP} = \begin{pmatrix} a \\ b \end{pmatrix}$, then its magnitude $= |\vec{OP}| = \sqrt{a^2 + b^2}$



Q1. i. If $\vec{OP} = \begin{pmatrix} 6 \\ 5 \end{pmatrix}$, find the magnitude of $\vec{OP}$.

ii. Find ϕ the angle between $\vec{OP}$ and the x – axis

Soln.



i. $|\vec{OP}| = \sqrt{6^2 + 5^2} = \sqrt{61} = 7.8$

ii. $\tan \phi = \frac{5}{6} \Rightarrow \tan \phi = 0.83 \Rightarrow \phi = \tan^{-1} 0.83 \Rightarrow \phi = 40^\circ$

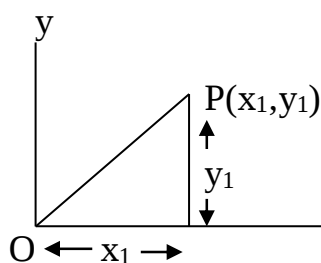
Scalar multiplication of vector:

- If λ is the scalar and $\vec{a}$ is the vector, then the scalar $\times$ the vector $= \lambda \vec{a}$
- When a scalar multiplies a vector, the product is also a vector, and for this reason $\lambda \vec{a}$ is also a vector.
- The vector $\lambda \vec{a}$ is parallel to $\vec{a}$, and is in the same direction as $\vec{a}$, but has λ times the magnitude of $\vec{a}$.
- For example the vectors $\vec{a}$ and $2\vec{a}$ have the same direction.

i.e. $\underbrace{\quad\quad\quad}_{|\vec{a}|} \quad \underbrace{\quad\quad\quad}_{|2\vec{a}|}$

- But the vectors $\vec{a}$ and $-2\vec{a}$ are opposite in direction.
- $\lambda(\vec{a} + \vec{b}) = \lambda\vec{a} + \lambda\vec{b}$, e.g. $6(\vec{a} + \vec{b}) = 6\vec{a} + 6\vec{b}$
- Also $(2 + 4)\vec{a} = 2\vec{a} + 4\vec{a}$
- Finally $\lambda_1(\lambda_2\vec{a}) = \lambda_1\lambda_2\vec{a}$, e.g. $3(2\vec{a}) = 6\vec{a}$

N/B:



- If $P(x_1, y_1)$ is a point in the $x - y$ plane, then the position vector of P relative to the origin, O is defined by $\vec{OP} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix}$
- Also if $A = (0, 6)$, then $\vec{OA} = \begin{pmatrix} 0 \\ 6 \end{pmatrix}$

Q2. Find the numbers m and n such that

$$m\begin{pmatrix} 3 \\ 5 \end{pmatrix} + n\begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 9 \end{pmatrix}$$

Soln.

$$m\begin{pmatrix} 3 \\ 5 \end{pmatrix} + n\begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 9 \end{pmatrix} \Rightarrow \begin{pmatrix} 3m \\ 5m \end{pmatrix} + \begin{pmatrix} 2n \\ n \end{pmatrix} = \begin{pmatrix} 4 \\ 9 \end{pmatrix}$$

$$\Rightarrow 3m + 2n = 4 \dots \dots \text{eqn(1)}.$$

$$5m + n = 9 \dots \dots \dots \text{eqn(2)}$$

Solve eqns (1) and (2) simultaneously

$$\Rightarrow m = 2 \text{ and } n = -1$$

Q3. If $mp + nq = \begin{pmatrix} 4 \\ 3 \end{pmatrix}$, find m and n where m and n are scalar, given that $p = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ and $q = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$

Soln.

$$p = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \text{ and } q = \begin{pmatrix} 2 \\ 5 \end{pmatrix} \text{ but } mp + nq = \begin{pmatrix} 4 \\ 3 \end{pmatrix}$$

$$\Rightarrow m \begin{pmatrix} 2 \\ 3 \end{pmatrix} + n \begin{pmatrix} 2 \\ 5 \end{pmatrix} = \begin{pmatrix} 4 \\ 3 \end{pmatrix} \Rightarrow \begin{pmatrix} 2m \\ 3m \end{pmatrix} + \begin{pmatrix} 2n \\ 5n \end{pmatrix} = \begin{pmatrix} 4 \\ 3 \end{pmatrix}$$

$$\Rightarrow 2m + 2n = 4 \dots (1)$$

$$3m + 5n = 3 \dots (2)$$

Solve eqns (1) and (2) simultaneously to get the values of m and n .

Q4. If $r = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ and $s = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$, evaluate $6(r + 2s)$

Soln.

$$\text{Consider } 6(r + 2s), \text{ solve what is inside the bracket first } \Rightarrow r + 2s = \begin{pmatrix} 3 \\ 1 \end{pmatrix} + 2 \begin{pmatrix} -2 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} + 2 \begin{pmatrix} -4 \\ 2 \end{pmatrix} \Rightarrow r + 2s = \begin{pmatrix} 3+(-4) \\ 1+2 \end{pmatrix} = \begin{pmatrix} -1 \\ 3 \end{pmatrix} \Rightarrow 6(r + 2s) = 6 \begin{pmatrix} -1 \\ 3 \end{pmatrix} = \begin{pmatrix} -6 \\ 18 \end{pmatrix}$$

Q5. If $p = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$, $q = \begin{pmatrix} -2 \\ 3 \end{pmatrix}$ and $r = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, find $2p - q + r$

Soln.

$$2p - q + r = 2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} -2 \\ 3 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \end{pmatrix} - \begin{pmatrix} -2 \\ 3 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2+2+1 \\ 4-3+1 \end{pmatrix} = \begin{pmatrix} 5 \\ 2 \end{pmatrix} \Rightarrow 2p - q + r = \begin{pmatrix} 5 \\ 2 \end{pmatrix}.$$

Q6. If the vector $p = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$, $q = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$ and $r = \frac{1}{2}(q - p)$,

Find the vector r .

Soln.

$$r = \frac{1}{2}(q - p) \Rightarrow r = \frac{1}{2}\left\{\begin{pmatrix} 2 \\ 5 \end{pmatrix} - \begin{pmatrix} 2 \\ 3 \end{pmatrix}\right\} \Rightarrow r = \frac{1}{2}\begin{Bmatrix} 2-2 \\ 5-3 \end{Bmatrix} = \frac{1}{2}\begin{Bmatrix} 0 \\ 2 \end{Bmatrix} = \begin{Bmatrix} \frac{1}{2}(0) \\ \frac{1}{2}(2) \end{Bmatrix} = \begin{Bmatrix} 0 \\ 1 \end{Bmatrix} \Rightarrow r = \begin{Bmatrix} 0 \\ 1 \end{Bmatrix}$$

N/B: Given the points A and B, then $\overrightarrow{AB} = B - A$.